

# YDLIDAR TEA DATA SHEET<sup>ALPHA</sup>



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# YOLIDAR Make robots serve people better

# **1 PRODUCT OVERVIEW**

YDLIDAR TEA is a series of 2D LiDAR (hereinafter referred to as TEA) developed by EAI team. Based on ToF principle, TEA is based on the single-line scanning design and can output 30k point cloud data per second. It adopts 905nm infrared excitation light, with the self-developed signal processing algorithm, to meet the requirement of outdoor application scenarios. TEA also adopts industrial interface design to transmit point cloud data through network protocol, and the dustproof and waterproof of the whole device reaches IP65 level. TEA structure design is compact, easy to integrate, and provides a complete integrated development interface, widely used in robot navigation and obstacle avoidance, environmental scanning and mapping, industrial AGV, assisted driving and other fields.

#### **1.1 Product Features**

- ➢ High speed range and frequency range of 30kHz
- Ranging repeat of high precision, good consistency
- ➢ 300 degrees horizontal view
- Maximum 30Hz scanning frequency can be configured
- Strong resistance to ambient light interference
- > IP65 protection level of dustproof and waterproof
- > 100M adaptive network interface for data transmission

# **1.2 Applications**

- Robot navigation and obstacle avoidance
- Industrial automation
- Regional security
- ➢ Smart transportation
- Environmental scanning and 3D reconstruction
- Digital multimedia interaction
- Robot ROS teaching and research

# **1.3 Installation and Dimensions**

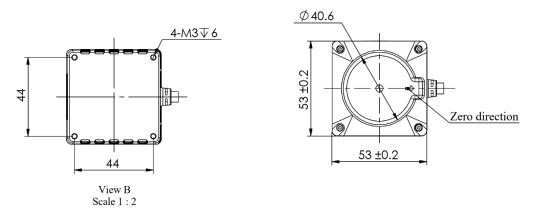


FIG 1 YDLIDAR TIA INSTALLATION DIMENSION (UNIT:MM)



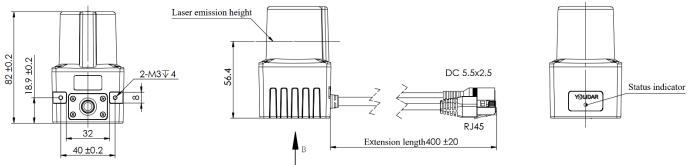


FIG 2 YDLIDAR TIA MECHANICAL DIMENSION (UNIT:MM)

# **2 SPECIFICATIONS**

### 2.1 Performance Parameter

#### **CHART 1 YDLIDAR TEA PERFORMANCE PARAMETER**

Item	Min	Typical	Max	Unit	Remarks
Ranging frequency	/	30000	/	Hz	/
Scanning frequency	15	20	30	Hz	Software control
Densing distance	0.05	/	25	m	80% reflectivity
Ranging distance	0.05	/	10	m	10% reflectivity
Field of view	/	300	/	Deg	/
Systematic error	/	/	±3	mm	/
Angle resolution	0.12 (10Hz)	0.24 (20Hz)	0.36 (30Hz)	Deg	Ranging frequency=30kHz

Note 1: It is factory FQC standard value, 80% reflectivity material object.

Note 2: Lidar is a precision device, please avoid using Lidar under high or low temperature or strong vibration situation, the systematic error parameter index will be relatively larger, and it may exceed the typical value.

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# 2.2 Physical Parameters

#### **CHART 2 YDLIDAR TEA PHYSICAL PARAMETERS**

Item	Min	Typical	Max	Unit	Remarks
Supply voltage	9	12	28	V	/
Operating power	/	TBD	/	W	/
Operating temperature	-10	25	50	°C	/
Laser wavelength	895	905	915	nm	/
Lighting environment	/	80000	/	lux	For reference only, the laser transceiver window cannot be directly facing the strong light source such as the sun
Degree of protection	/	IP65	/	/	/
Weight	/	TBD	/	g	N.W.
Dimension	/	53*53*82	/	mm	W*H*D

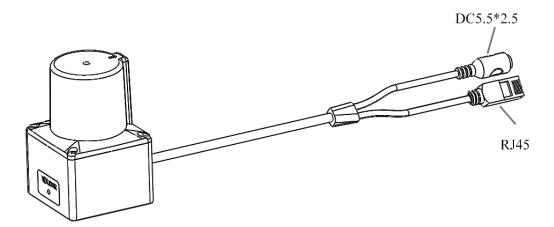
### 2.3 Default Settings

#### **CHART 3 YDLIDAR TEA DEFAULT SETTINGS**

Item	Default value	Remarks
Network IP	192.168.0.11	configurable
Ranging zero	Center point of lidar	unconfigurable
Direction of rotation	Clockwise (top view)	unconfigurable
Angle zero	Arrow direction on top of protective cover	configurable
Indicator light	Steady red: The system is in standby state Steady green: The system is working	unconfigurable

### 2.4 Interface Definition

TEA has its own connection cables, and the cable is separated into the network port and the power port by splitting in two. The RJ45 network interface is used for data transmission and supports 10M/100M adaptive network. The DC5.5\*2.5 interface for power supply, support wide voltage input (9-28V).





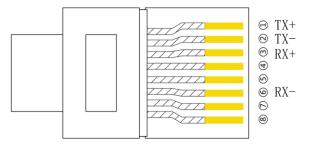
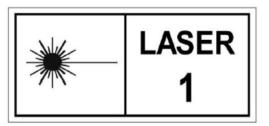


FIG 3 YDLIDAR TEA INTERFACES

Note: The pigtail length is 40cm.

### 2.5 Optical Characteristic

The infrared point pulse laser used in TEA can ensure the safety of human and pet. The lidar has passed testing and conformed to Class I, 21 CFR 1040.10 and 1040. 11 safety level, except for IEC 60825-1 Ed. 3., as described in Laser Notice No. 56, dated May 8, 2019.



The laser and optical lens finish the transmission and reception of the laser signal to achieve high-frequency ranging while working. The detailed optical parameters are as follows:

#### **CHART 1 YDLIDAR T-MINI PRO LASER OPTICAL PARAMETERS**

Item	Min	Typical	Max	Unit	Remarks
Laser wavelength	895	905	915	nm	Infrared band
FDA	Class I IEC60825-1				

Note: The personal adjustment or reassembly of the Lidar may result inhazardousradiation exposure.

### 2.6 Polar Coordinate System Definition

In order to facilitate secondary development, TEA internally defines a polar coordinate system. The polar coordinates of the system take the center of the rotating core of TEA as the pole, and the specified Angle is positive clockwise (top view). The zero Angle is located in the direction of the arrow at the top of the protective cover, as shown in the figure:

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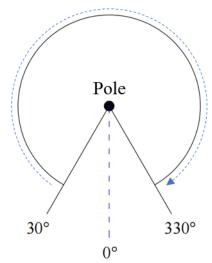


FIG 4 YDLIDAR TG5 POLAR COORDINATE SYSTEM DEFINITION

# **3 DEVELOPMENT AND SUPPORT**

TEA provides a wealth of software interfaces, which can realize the motor enabling control, speed control, range unit enabling control and output control of the system. On this basis, users can also implement the power control and scan control purpose.

Also, the 3D model of TEA is disclosed. YDLIDAR provides the graphics debugging Workstation under Windows, as well as the corresponding SDK and ROS development kit to users, which could be downloaded from our website: <u>https://www.ydlidar.com/</u>.

In order to facilitate users' development, TEA development manual, SDK development manual and ROS user manual are also provided. Please download them from <u>our website</u>.

# **Y** LIDAR Make robots serve people better **4** REVISION

Date	Version	Content		
2023-03-14	0.1.0	The 1st release		
2023-08-09	0.1.1	Update operating temperature		
2023-10-12	0.1.2	<ol> <li>Update Section 1.3 drawings</li> <li>Update Chart 1 measurement accuracy</li> <li>Update Chart 2 dimensions</li> </ol>		